## **Basis of Real Linear Space**

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**Summary.** Notions of linear independence and dependence of set of vectors, the subspace generated by a set of vectors and basis of real linear space are introduced. Some theorems concerning those notions are proved.

MML Identifier: RLVECT\_3.
WWW: http://mizar.org/JFM/Vol2/rlvect\_3.html

The articles [8], [6], [16], [10], [3], [17], [2], [4], [5], [14], [9], [7], [13], [12], [11], [15], and [1] provide the notation and terminology for this paper.

For simplicity, we follow the rules: x, X, Y, Z are sets, a, b are real numbers, V is a real linear space,  $W_1, W_2, W_3$  are subspaces of  $V, v, v_1, v_2$  are vectors of V, A, B are subsets of  $V, L, L_1, L_2$  are linear combinations of V, l is a linear combination of A, F, G are finite sequences of elements of the carrier of V, f is a function from the carrier of V into  $\mathbb{R}, M$  is a non empty set, and  $C_1$  is a choice function of M.

The following four propositions are true:

- (1)  $\Sigma(L_1 + L_2) = \Sigma L_1 + \Sigma L_2.$
- (2)  $\Sigma(a \cdot L) = a \cdot \Sigma L.$
- (3)  $\Sigma(-L) = -\Sigma L.$
- (4)  $\Sigma(L_1 L_2) = \Sigma L_1 \Sigma L_2.$

Let us consider V and let us consider A. We say that A is linearly independent if and only if:

(Def. 1) For every *l* such that  $\sum l = 0_V$  holds the support of  $l = \emptyset$ .

We introduce *A* is linearly dependent as an antonym of *A* is linearly independent. Next we state several propositions:

- (6)<sup>1</sup> If  $A \subseteq B$  and B is linearly independent, then A is linearly independent.
- (7) If *A* is linearly independent, then  $0_V \notin A$ .
- (8)  $\emptyset_{\text{the carrier of } V}$  is linearly independent.
- (9)  $\{v\}$  is linearly independent iff  $v \neq 0_V$ .
- (10)  $\{0_V\}$  is linearly dependent.
- (11) If  $\{v_1, v_2\}$  is linearly independent, then  $v_1 \neq 0_V$  and  $v_2 \neq 0_V$ .

<sup>&</sup>lt;sup>1</sup> The proposition (5) has been removed.

- (12)  $\{v, 0_V\}$  is linearly dependent and  $\{0_V, v\}$  is linearly dependent.
- (13)  $v_1 \neq v_2$  and  $\{v_1, v_2\}$  is linearly independent iff  $v_2 \neq 0_V$  and for every *a* holds  $v_1 \neq a \cdot v_2$ .
- (14)  $v_1 \neq v_2$  and  $\{v_1, v_2\}$  is linearly independent iff for all a, b such that  $a \cdot v_1 + b \cdot v_2 = 0_V$  holds a = 0 and b = 0.

Let us consider V and let us consider A. The functor Lin(A) yields a strict subspace of V and is defined by:

(Def. 2) The carrier of  $Lin(A) = \{\sum l\}$ .

Next we state a number of propositions:

- $(17)^2$   $x \in \text{Lin}(A)$  iff there exists l such that  $x = \sum l$ .
- (18) If  $x \in A$ , then  $x \in Lin(A)$ .
- (19)  $\operatorname{Lin}(\emptyset_{\operatorname{the carrier of }V}) = \mathbf{0}_V.$
- (20) If  $Lin(A) = \mathbf{0}_V$ , then  $A = \emptyset$  or  $A = \{0_V\}$ .
- (21) For every strict subspace W of V such that A = the carrier of W holds Lin(A) = W.
- (22) For every strict real linear space V and for every subset A of V such that A = the carrier of V holds Lin(A) = V.
- (23) If  $A \subseteq B$ , then Lin(A) is a subspace of Lin(B).
- (24) For every strict real linear space V and for all subsets A, B of V such that Lin(A) = V and  $A \subseteq B$  holds Lin(B) = V.
- (25)  $\operatorname{Lin}(A \cup B) = \operatorname{Lin}(A) + \operatorname{Lin}(B).$
- (26)  $\operatorname{Lin}(A \cap B)$  is a subspace of  $\operatorname{Lin}(A) \cap \operatorname{Lin}(B)$ .
- (27) Suppose *A* is linearly independent. Then there exists *B* such that  $A \subseteq B$  and *B* is linearly independent and Lin(B) = the RLS structure of *V*.
- (28) If Lin(A) = V, then there exists B such that  $B \subseteq A$  and B is linearly independent and Lin(B) = V.

Let *V* be a real linear space. A subset of *V* is called a basis of *V* if:

(Def. 3) It is linearly independent and Lin(it) = the RLS structure of V.

In the sequel *I* denotes a basis of *V*. The following propositions are true:

- $(32)^3$  Let V be a strict real linear space and A be a subset of V. If A is linearly independent, then there exists a basis I of V such that  $A \subseteq I$ .
- (33) If Lin(A) = V, then there exists *I* such that  $I \subseteq A$ .
- (34) If  $Z \neq \emptyset$  and Z is finite and for all X, Y such that  $X \in Z$  and  $Y \in Z$  holds  $X \subseteq Y$  or  $Y \subseteq X$ , then  $\bigcup Z \in Z$ .
- (35) If  $\emptyset \notin M$ , then dom  $C_1 = M$  and rng  $C_1 \subseteq \bigcup M$ .
- (36)  $x \in \mathbf{0}_V$  iff  $x = 0_V$ .
- (37) If  $W_1$  is a subspace of  $W_3$ , then  $W_1 \cap W_2$  is a subspace of  $W_3$ .

 $<sup>^{2}</sup>$  The propositions (15) and (16) have been removed.

<sup>&</sup>lt;sup>3</sup> The propositions (29)–(31) have been removed.

- (38) If  $W_1$  is a subspace of  $W_2$  and a subspace of  $W_3$ , then  $W_1$  is a subspace of  $W_2 \cap W_3$ .
- (39) If  $W_1$  is a subspace of  $W_3$  and  $W_2$  is a subspace of  $W_3$ , then  $W_1 + W_2$  is a subspace of  $W_3$ .
- (40) If  $W_1$  is a subspace of  $W_2$ , then  $W_1$  is a subspace of  $W_2 + W_3$ .
- (41)  $f(F \cap G) = (fF) \cap (fG).$

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Received July 10, 1990

Published January 2, 2004